empymod Documentation

Release 1.4.4

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The electromagnetic modeller **empymod** can model electric or magnetic responses due to a three-dimensional electric or magnetic source in a layered-earth model with vertical transverse isotropic (VTI) resistivity, VTI electric permittivity, and VTI magnetic permeability, from very low frequencies (DC) to very high frequencies (GPR). The calculation is carried out in the wavenumber-frequency domain, and various Hankel- and Fourier-transform methods are included to transform the responses into the space-frequency and space-time domains.

Contents: The latest version of this documentation can be found at https://empymod.readthedocs.io.

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CHAPTER 1

Installation & requirements

The easiest way to install the latest stable version of *empymod* is via *conda*:

```
> conda install -c prisae empymod
```

or via *pip*:

```
> pip install empymod
```

Alternatively, you can download the latest version from GitHub and either add the path to *empymod* to your python-path variable, or install it in your python distribution via:

```
> python setup.py install
```

Required are python version 3.4 or higher and the modules *NumPy* and *SciPy*. If you want to run parts of the kernel in parallel, the module *numexpr* is required additionally.

Note: Do not use scipy == 0.19.0. It has a memory leak in quad, see github.com/scipy/scipy/pull/7216. So if you use QUAD (or potentially QWE) in any of your transforms you might see your memory usage going through the roof.

If you are new to Python I recommend using a Python distribution, which will ensure that all dependencies are met, specifically properly compiled versions of *NumPy* and *SciPy*; I recommend using Anaconda (version 3.x; anaconda.com/download). If you install Anaconda you can simply start the *Anaconda Navigator*, add the channel *prisae* and *empymod* will appear in the package list and can be installed with a click.

Usage

The main modelling routines is *bipole*, which can calculate the electromagnetic frequency- or time-domain field due to arbitrary finite electric or magnetic bipole sources, measured by arbitrary finite electric or magnetic bipole receivers. The model is defined by horizontal resistivity and anisotropy, horizontal and vertical electric permittivities and horizontal and vertical magnetic permeabilities. By default, the electromagnetic response is normalized to source and receiver of 1 m length, and source strength of 1 A.

A simple frequency-domain example, with most of the parameters left at the default value:

```
>>> import numpy as np
>>> from empymod import bipole
>>> # x-directed bipole source: x0, x1, y0, y1, z0, z1
\rightarrow \rightarrow src = [-50, 50, 0, 0, 100, 100]
>>> # x-directed dipole source-array: x, y, z, azimuth, dip
>>> rec = [np.arange(1, 11)*500, np.zeros(10), 200, 0, 0]
>>> # layer boundaries
>>> depth = [0, 300, 1000, 1050]
>>> # layer resistivities
>>> res = [1e20, .3, 1, 50, 1]
>>> # Frequency
>>> freq = 1
>>> # Calculate electric field due to an electric source at 1 Hz.
>>> # [msrc = mrec = True (default)]
>>> EMfield = bipole(src, rec, depth, res, freq, verb=4)
:: empymod START ::
           [m] : 0 300 1000 1050
  depth
          [Ohm.m] : 1E+20 0.3 1 50 1
  res
           [-] : 1 1 1 1 1
  aniso
             [-]: 1 1 1 1 1
  epermH
            [-]: 11111
  epermV
  mpermH
mpermV
             [-]: 1 1 1 1 1
             [-]: 1 1 1 1 1
  frequency [Hz] : 1
  Hankel : Fast Hankel Transform
  > Filter : Key 201 (2009)
> pts_per_dec : Defined by filter (lagged)
Hankel Opt. : None
  Loop over : None (all vec
Source(s) : 1 bipole(s)
> intpts : 1 (as dipole)
                 : None (all vectorized)
    > length [m] : 100
    > x_c [m] : 0
    > V_C
             [m] : 0
    > z_c [m] : 100
    > azimuth [°] : 0
    > dip [°]: 0
   Receiver(s) : 10 dipole(s)
    > x [m] : 500 - 5000 : 10 [min-max; #]
                  : 500 1000 1500 2000 2500 3000 3500 4000 4500 5000
              [m] : 0 - 0 : 10 [min-max; #]
                  : 0 0 0 0 0 0 0 0 0 0
              [m] : 200
    > z
    > azimuth [°] : 0
    > dip [°]: 0
  Required ab's : 11
:: empymod END; runtime = 0:00:00.005536 :: 1 kernel call(s)
>>> print (EMfield)
[ 1.68809346e-10 -3.08303130e-10j -8.77189179e-12 -3.76920235e-11j
  -3.46654704e-12 -4.87133683e-12j -3.60159726e-13 -1.12434417e-12j
  1.87807271e-13 -6.21669759e-13j 1.97200208e-13 -4.38210489e-13j
  1.44134842e-13 -3.17505260e-13j 9.92770406e-14 -2.33950871e-13j
   6.75287598e-14 -1.74922886e-13j 4.62724887e-14 -1.32266600e-13j]
```

Frequency- and time-domain examples can be found in the empymod/example-notebooks-repository.

More information and more examples can be found in the following articles:

- empymod/article-geo2017 (doi: 10.1190/geo2016-0626.1)
- empymod/article-tle2017 (doi: 10.1190/tle36040352.1)

Structure

- model.py: EM modelling routines.
- utils.py: Utilities for model such as checking input parameters.
- **kernel.py**: Kernel of *empymod*, calculates the wavenumber-domain electromagnetic response. Plus analytical, frequency-domain full- and half-space solutions.
- **transform.py**: Methods to carry out the required Hankel transform from wavenumber to space domain and Fourier transform from frequency to time domain.
- filters.py: Filters for the Fast Hankel Transform FHT [Anderson_19820], and the Fourier Sine and Cosine Transforms [Anderson_19750].

Missing features

A list of things that should or could be added and improved can be found in the Roadmap.

Testing

The modeller comes with a test suite using *pytest*. If you want to run the tests, just install *pytest* and run it within the *empymod*-top-directory.

```
> conda install pytest
> # or
> pip install pytest
> # and then
> cd to/the/empymod/folder # Ensure you are in the right directory,
> ls -d */ # your output should look the same.
docs/ empymod/ tests/
> # pytest will find the tests, which are located in the tests-folder.
> # simply run
> pytest
```

It should run all tests successfully. Please let me know if not!

Note that installations of *empymod* via conda or pip do not have the test-suite included. To run the test-suite you must download *empymod* from GitHub.

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CHAPTER 2

Info

Citation

If you publish results for which you used empymod, please give credit by citing this article:

Werthmüller, D., 2017, An open-source full 3D electromagnetic modeler for 1D VTI media in Python: empymod: Geophysics, 82, WB9–WB19; DOI: 10.1190/geo2016-0626.1.

Also consider citing [Hunziker_et_al_20150] and [Key_20120], without which empymod would not existk All releases have a Zenodo-DOI, provided on the release-page.

Notice

This product includes software that was initially (till 01/2017) developed at *The Mexican Institute of Petroleum IMP* (*Instituto Mexicano del Petróleo*, http://www.gob.mx/imp). The project was funded through *The Mexican National Council of Science and Technology* (*Consejo Nacional de Ciencia y Tecnología*, http://www.conacyt.mx). Since 02/2017 it is a personal effort, and new contributors are welcome!

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8 Chapter 2. Info

Note on speed, memory, and accuracy

There is the usual trade-off between speed, memory, and accuracy. Very generally speaking we can say that the *FHT* is faster than *QWE*, but *QWE* is much easier on memory usage. *QWE* allows you to control the accuracy. A standard quadrature in the form of *QUAD* is also provided. *QUAD* is generally orders of magnitudes slower, and more fragile depending on the input arguments. However, it can provide accurate results where *FHT* and *QWE* fail.

There are two optimisation possibilities included via the opt-flag: parallelisation (opt='parallel') and spline interpolation (opt='spline'). They are switched off by default. The optimization opt='parallel' only affects speed and memory usage, whereas opt='spline' also affects precision!

I am sure *empymod* could be made much faster with cleverer coding style or with the likes of *cython* or *numba*. Suggestions and contributions are welcomed!

Included transforms

Hankel transform:

- Fast Hankel Transform *FHT* ([Gosh_19710])
- Quadrature with Extrapolation QWE ([Key_20120])
- Adaptive quadrature *QUAD* (from *QUADPACK*)

Fourier transform:

- Sine- and Cosine filters ([Anderson_19750])
- Quadrature with Extrapolation *QWE* ([Key_20120])
- Fast Fourier Transform FFT
- Logarithmic Fast Fourier Transform FFTLog ([Hamilton_20000])

FFTLog

FFTLog is the logarithmic analogue to the Fast Fourier Transform FFT originally proposed by [Talman_19780]. The code used by empymod was published in Appendix B of [Hamilton_20000] and is publicly available at casa.colorado.edu/~ajsh/FFTLog. From the FFTLog-website:

FFTLog is a set of fortran subroutines that compute the fast Fourier or Hankel (= Fourier-Bessel) transform of a periodic sequence of logarithmically spaced points.

FFTlog can be used for the Hankel as well as for the Fourier Transform, but currently *empymod* uses it only for the Fourier transform. It uses a simplified version of the python implementation of FFTLog, *pyfftlog* (github.com/prisae/pyfftlog).

[Haines_and_Jones_19880] proposed a logarithmic Fourier transform (abbreviated by the authors as LFT) for electromagnetic geophysics, also based on [Talman_19780]. I do not know if Hamilton was aware of the work by Haines and Jones. The two publications share as reference only the original paper by Talman, and both cite a publication of Anderson; Hamilton cites [Anderson_19820], and Haines and Jones cite [Anderson_19790]. Hamilton probably never heard of Haines and Jones, as he works in astronomy, and Haines and Jones was published in the Geophysical Journal.

Logarithmic FFTs are not widely used in electromagnetics, as far as I know, probably because of the ease, speed, and generally sufficient precision of the digital filter methods with sine and cosine transforms ([Anderson_19750]). However, comparisons show that FFTLog can be faster and more precise than digital filters, specifically for responses with source and receiver at the interface between air and subsurface. Credit to use FFTLog in electromagnetics goes to David Taylor who, in the mid-2000s, implemented FFTLog into the forward modellers of the company Multi-Transient ElectroMagnetic (MTEM Ltd, later Petroleum Geo-Services PGS). The implementation was driven by land responses, where FFTLog can be much more precise than the filter method for very early times.

Notes on Fourier Transform

The Fourier transform to obtain the space-time domain impulse response from the complex-valued space-frequency response can be calculated by either a cosine transform with the real values, or a sine transform with the imaginary part,

$$\begin{split} E(r,t)^{\text{Impulse}} &= \; \frac{2}{\pi} \int_0^\infty \Re[E(r,\omega)] \cos(\omega t) \; \mathrm{d}\omega \;, \\ &= -\frac{2}{\pi} \int_0^\infty \Im[E(r,\omega)] \sin(\omega t) \; \mathrm{d}\omega \;, \end{split}$$

see, e.g., [Anderson_19750] or [Key_20120]. Quadrature-with-extrapolation, FFTLog, and obviously the sine/cosine-transform all make use of this split.

To obtain the step-on response the frequency-domain result is first divided by $i\omega$, in the case of the step-off response it is additionally multiplied by -1. The impulse-response is the time-derivative of the step-response,

$$E(r,t)^{\rm Impulse} = \frac{\partial \ E(r,t)^{\rm step}}{\partial t} \ .$$

Using $\frac{\partial}{\partial t} \Leftrightarrow i\omega$ and going the other way, from impulse to step, leads to the divison by $i\omega$. (This only holds because we define in accordance with the causality principle that $E(r,t\leq 0)=0$).

With the sine/cosine transform (ft='ffht'/'sin'/'cos') you can choose which one you want for the impulse responses. For the switch-on response, however, the sine-transform is enforced, and equally the cosine transform for the switch-off response. This is because these two do not need to now the field at time 0, E(r,t=0).

The Quadrature-with-extrapolation and FFTLog are hard-coded to use the cosine transform for step-off responses, and the sine transform for impulse and step-on responses. The FFT uses the full complex-valued response at the moment.

For completeness sake, the step-on response is given by

$$E(r,t)^{ ext{Step-on}} = -rac{2}{\pi} \int_0^\infty \Im \left[rac{E(r,\omega)}{i\omega}
ight] \sin(\omega t) \,\mathrm{d}\omega \;,$$

and the step-off by

$$E(r,t)^{ ext{Step-off}} = -rac{2}{\pi} \int_0^\infty \Re \left[rac{E(r,\omega)}{i\omega}
ight] \cos(\omega t) \; \mathrm{d}\omega \; .$$

Depths, Rotation, and Bipole

Depths: Calculation of many source and receiver positions is fastest if they remain at the same depth, as they can be calculated in one kernel-call. If depths do change, one has to loop over them. Note: Sources or receivers placed on a layer interface are considered in the upper layer.

Rotation: Sources and receivers aligned along the principal axes x, y, and z can be calculated in one kernel call. For arbitrary oriented di- or bipoles, 3 kernel calls are required. If source and receiver are arbitrary oriented, 9 (3x3) kernel calls are required.

Bipole: Bipoles increase the calculation time by the amount of integration points used. For a source and a receiver bipole with each 5 integration points you need 25 (5x5) kernel calls. You can calculate it in 1 kernel call if you set both integration points to 1, and therefore calculate the bipole as if they were dipoles at their centre.

Example: For 1 source and 10 receivers, all at the same depth, 1 kernel call is required. If all receivers are at different depths, 10 kernel calls are required. If you make source and receivers bipoles with 5 integration points, 250 kernel calls are required. If you rotate the source arbitrary horizontally, 500 kernel calls are required. If you rotate the receivers too, in the horizontal plane, 1'000 kernel calls are required. If you rotate the receivers also vertically, 1'500 kernel calls are required. If you rotate the source vertically too, 2'250 kernel calls are required. So your calculation will take 2'250 times longer! No matter how fast the kernel is, this will take a long time. Therefore carefully plan how precise you want to define your source and receiver bipoles.

Table 3.1: Example as a table for comparison: 1 source, 10 receiver (one or many frequencies).

	source	bipole		receiver bipole			
kernel calls	intpts	azimuth	dip	intpts	azimuth	dip	diff. z
1	1	0/90	0/90	1	0/90	0/90	1
10	1	0/90	0/90	1	0/90	0/90	10
250	5	0/90	0/90	5	0/90	0/90	10
500	5	arb.	0/90	5	0/90	0/90	10
1000	5	arb.	0/90	5	arb.	0/90	10
1500	5	arb.	0/90	5	arb.	arb.	10
2250	5	arb.	arb.	5	arb.	arb.	10

Parallelisation

If opt = 'parallel', a good dozen of the most time-consuming statements are calculated by using the *numexpr* package (https://github.com/pydata/numexpr/wiki/Numexpr-Users-Guide). These statements are all in the *kernel*-functions *greenfct*, *reflections*, and *fields*, and all involve Γ in one way or another, often calculating square roots or exponentials. As Γ has dimensions (#frequencies, #offsets, #layers, #lambdas), it can become fairly big.

The module *numexpr* uses by default all available cores up to a maximum of 8. You can change this behaviour to a lower or a higher value with the following command (in the example it is changed to 4):

```
>>> import numexpr
>>> numexpr.set_num_threads(4)
```

This parallelisation will make *empymod* faster if you calculate a lot of offsets/frequencies at once, but slower for few offsets/frequencies. Best practice is to check first which one is faster. (You can use the benchmark-notebook in the empymod/example-notebooks-repository.)

Spline interpolation

If opt = 'spline', the so-called *lagged convolution* or *splined* variant of the *FHT* (depending on htarg) or the *splined* version of the *QWE* are applied. The spline option should be used with caution, as it is an interpolation and therefore less precise than the non-spline version. However, it significantly speeds up *QWE*, and massively speeds up *FHT*. (The *numexpr*-version of the spline option is slower than the pure spline one, and therefore it is only possible to have either 'parallel' or 'spline' on.)

Setting opt = 'spline' is generally faster. Good speed-up is achieved for *QWE* by setting maxint as low as possible. Also, the higher nquad is, the higher the speed-up will be. The variable pts_per_dec has also some influence. For *FHT*, big improvements are achieved for long FHT-filters and for many offsets/frequencies (thousands). Additionally, spline minimizes memory requirements a lot. Speed-up is greater if all source-receiver angles are identical.

FHT: Default for pts_per_dec = None, which is the original lagged convolution, where the spacing is defined by the filter-base, the transform is carried out first followed by spline-interpolation. You can set this parameter to an integer, which defines the number of points to evaluate per decade. In this case the spline-interpolation is carried out first, followed by the transformation. The original lagged convolution is generally the fastest for a very good precision. However, by setting pts_per_dec appropriately one can achieve higher precision, normally at the cost of speed.

Warning: Keep in mind that it uses interpolation, and is therefore not as accurate as the non-spline version. Use with caution and always compare with the non-spline version if you can apply the spline-version to your problem at hand!

Be aware that *QUAD* (Hankel transform) *always* use the splined version and *always* loop over offsets. The same applies for all frequency-to-time transformations.

The splined versions of *QWE* check whether the ratio of any two adjacent intervals is above a certain threshold (steep end of the wavenumber or frequency spectrum). If it is, it carries out *QUAD* for this interval instead of *QWE*. The threshold is stored in *diff_quad*, which can be changed within the parameter *htarg* and *ftarg*.

Looping

By default, you can calculate many offsets and many frequencies all in one go, vectorized (for the *FHT*), which is the default. The loop parameter gives you the possibility to force looping over frequencies or offsets. This parameter can have severe effects on both runtime and memory usage. Play around with this factor to find the fastest version for your problem at hand. It ALWAYS loops over frequencies if ht = 'QWE'/'QUAD' or if opt = 'spline'. All vectorized is very fast if there are few offsets or few frequencies. If there are many offsets and many frequencies, looping over the smaller of the two will be faster. Choosing the right looping together with opt = 'parallel' can have a huge influence.

Vertical components

It is advised to use xdirect = True (the default) if source and receiver are in the same layer to calculate

- the vertical electric field due to a vertical electric source,
- configurations that involve vertical magnetic components (source or receiver),
- all configurations when source and receiver depth are exactly the same.

The Hankel transforms methods are having sometimes difficulties transforming these functions.

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CHAPTER 4

References

Code

model - Model EM-responses

EM-modelling routines. The implemented routines might not be the fastest solution to your specific problem. Use these routines as template to create your own, problem-specific modelling routine!

Principal routines:

- bipole
- dipole

The main routine is *bipole*, which can model bipole source(s) and bipole receiver(s) of arbitrary direction, for electric or magnetic sources and receivers, both in frequency and in time. A subset of *bipole* is *dipole*, which models infinitesimal small dipoles along the principal axes x, y, and z.

Further routines are:

- analytical: Calculate analytical fullspace and halfspace solutions.
- wavenumber: Calculate the electromagnetic wavenumber-domain solution.
- gpr: Calculate the Ground-Penetrating Radar (GPR) response.

The *wavenumber* routine can be used if you are interested in the wavenumber-domain result, without Hankel nor Fourier transform. It calls straight the *kernel*. The *gpr*-routine convolves the frequency-domain result with a wavelet, and applies a gain to the time-domain result. This function is still experimental.

The modelling routines make use of the following two core routines:

- fem: Calculate wavenumber-domain electromagnetic field and carry out the Hankel transform to the frequency domain.
- tem: Carry out the Fourier transform to time domain after fem.

```
empymod.model.bipole (src, rec, depth, res, freqtime, signal=None, aniso=None, epermH=None, epermV=None, mpermH=None, mpermV=None, msrc=False, srcpts=1, mrec=False, recpts=1, strength=0, xdirect=True, ht='fht', htarg=None, ft='sin', ftarg=None, opt=None, loop=None, verb=2)
```

Return the electromagnetic field due to an electromagnetic source.

Calculate the electromagnetic frequency- or time-domain field due to arbitrary finite electric or magnetic bipole sources, measured by arbitrary finite electric or magnetic bipole receivers. By default, the electromagnetic response is normalized to to source and receiver of 1 m length, and source strength of 1 A.

Parameters src, rec: list of floats or arrays

Source and receiver coordinates (m):

- [x0, x1, y0, y1, z0, z1] (bipole of finite length)
- [x, y, z, azimuth, dip] (dipole, infinitesimal small)

Dimensions:

- The coordinates x, y, and z (dipole) or x0, x1, y0, y1, z0, and z1 (bipole) can be single values or arrays.
- The variables x and y (dipole) or x0, x1, y0, and y1 (bipole) must have the same dimensions.
- The variable z (dipole) or z0 and z1 (bipole) must either be single values or having the same dimension as the other coordinates.
- The variables azimuth and dip must be single values. If they have different angles, you have to use the bipole-method (with srcpts/recpts = 1, so it is calculated as dipoles).

Angles (coordinate system is left-handed, positive z down (East-North-Depth):

- azimuth (°): horizontal deviation from x-axis, anti-clockwise.
- dip (°): vertical deviation from xy-plane downwards.

Sources or receivers placed on a layer interface are considered in the upper layer.

depth: list

Absolute layer interfaces z(m); #depth = #res - 1 (excluding +/- infinity).

res: array_like

Horizontal resistivities rho_h (Ohm.m); #res = #depth + 1.

freqtime: array_like

Frequencies f (Hz) if signal == None, else times t (s); (f, t > 0).

signal: {None, 0, 1, -1}, optional

Source signal, default is None:

- None: Frequency-domain response
- -1 : Switch-off time-domain response
- 0 : Impulse time-domain response
- +1 : Switch-on time-domain response

aniso: array_like, optional

Anisotropies lambda = sqrt(rho_v/rho_h) (-); #aniso = #res. Defaults to ones.

epermH, epermV: array_like, optional

Relative horizontal/vertical electric permittivities epsilon_h/epsilon_v (-); #epermH = #epermV = #res. Default is ones.

mpermH, mpermV: array_like, optional

Relative horizontal/vertical magnetic permeabilities mu_h/mu_v (-); #mpermH = #mpermV = #res. Default is ones.

msrc, mrec: boolean, optional

If True, source/receiver (msrc/mrec) is magnetic, else electric. Default is False.

srcpts, recpts: int, optional

Number of integration points for bipole source/receiver, default is 1:

- srcpts/recpts < 3 : bipole, but calculated as dipole at centre
- srcpts/recpts >= 3 : bipole

strength: float, optional

Source strength (A):

- If 0, output is normalized to source and receiver of 1 m length, and source strength of 1 A.
- If != 0, output is returned for given source and receiver length, and source strength.

Default is 0.

xdirect: bool, optional

If True and source and receiver are in the same layer, the direct field is calculated analytically in the frequency domain, if False it is calculated in the wavenumber domain. Defaults to True.

Flag to choose either the *Fast Hankel Transform* (FHT), the *Quadrature-With-Extrapolation* (QWE), or a simple *Quadrature* (QUAD) for the Hankel transform. Defaults to 'fht'.

htarg: dict or list, optional

Depends on the value for ht:

- If *ht* = 'fht': [filter, pts_per_dec]:
 - filter: string of filter name in *empymod.filters* or the filter method itself. (default: *empymod.filters.key_201_2009()*)
 - pts_per_dec: points per decade (only relevant if spline=True)

If none, standard lagged convolution is used. (default: None)

• If ht = 'qwe': [rtol, atol, nquad, maxint, pts_per_dec,

```
diff_quad, a, b, limit]:
```

- rtol: relative tolerance (default: 1e-12)
- atol: absolute tolerance (default: 1e-30)
- nguad: order of Gaussian quadrature (default: 51)

- maxint: maximum number of partial integral intervals (default: 40)
- pts_per_dec: points per decade; only relevant if opt='spline' (default: 80)
- diff_quad: criteria when to swap to QUAD (only relevant if opt='spline') (default: 100)
- a: lower limit for QUAD (default: first interval from QWE)
- b: upper limit for QUAD (default: last interval from QWE)
- limit: limit for quad (default: maxint)
- If *ht* = 'quad': [atol, rtol, limit, lmin, lmax, pts_per_dec]:
 - rtol: relative tolerance (default: 1e-12)
 - atol: absolute tolerance (default: 1e-20)
 - limit: An upper bound on the number of subintervals used in the adaptive algorithm (default: 500)
 - lmin: Minimum wavenumber (default 1e-6)
 - lmax: Maximum wavenumber (default 0.1)
 - pts_per_dec: points per decade (default: 40)

The values can be provided as dict with the keywords, or as list. However, if provided as list, you have to follow the order given above. A few examples, assuming ht = qwe:

- Only changing rtol: {'rtol': 1e-4} or [1e-4] or 1e-4
- Changing rtol and nquad: {'rtol': 1e-4, 'nquad': 101} or [1e-4, '', 101]
- Only changing diff_quad: {'diffquad': 10} or [', ', ', ', ', ', 10]
- ft: {'sin', 'cos', 'qwe', 'fftlog', 'fft'}, optional

Only used if *signal*!= None. Flag to choose either the Sine- or Cosine-Filter, the Quadrature-With-Extrapolation (QWE), the FFTLog, or the FFT for the Fourier transform. Defaults to 'sin'.

ftarg: dict or list, optional

Only used if *signal* !=None. Depends on the value for *ft*:

- If $ft = \text{`sin' or `cos': [filter, pts_per_dec]:}$
 - filter: string of filter name in empymod.filters or the filter method itself. (Default: empymod.filters.key 201 CosSin 2012())
 - pts_per_dec: points per decade. If none, standard lagged convolution is used. (Default: None)
- If ft = `qwe': [rtol, atol, nquad, maxint, pts_per_dec]:
 - rtol: relative tolerance (default: 1e-8)
 - atol: absolute tolerance (default: 1e-20)
 - nquad: order of Gaussian quadrature (default: 21)
 - maxint: maximum number of partial integral intervals (default: 200)
 - pts_per_dec: points per decade (default: 20)

- diff_quad: criteria when to swap to QUAD (default: 100)
- a: lower limit for QUAD (default: first interval from QWE)
- b: upper limit for QUAD (default: last interval from QWE)
- limit: limit for quad (default: maxint)
- If ft = 'fftlog': [pts_per_dec, add_dec, q]:
 - pts per dec: sampels per decade (default: 10)
 - add_dec: additional decades [left, right] (default: [-2, 1])
 - q: exponent of power law bias (default: 0); $-1 \le q \le 1$
- If ft = 'fft': [dfreq, nfreq, ntot]:
 - dfreq: Linear step-size of frequencies (default: 0.002)
 - nfreq: Number of frequencies (default: 2048)
 - ntot: Total number for FFT; difference between nfreq and ntot is padded with zeroes. This number is ideally a power of 2, e.g. 2048 or 4096 (default: nfreq).
 - pts_per_dec : points per decade (default: None)

Padding can sometimes improve the result, not always. The default samples from 0.002 Hz - 4.096 Hz. If pts_per_dec is set to an integer, calculated frequencies are logarithmically spaced with the given number per decade, and then interpolated to yield the required frequencies for the FFT.

The values can be provided as dict with the keywords, or as list. However, if provided as list, you have to follow the order given above. See *htarg* for a few examples.

opt : {None, 'parallel', 'spline'}, optional

Optimization flag. Defaults to None:

- None: Normal case, no parallelization nor interpolation is used.
- If 'parallel', the package *numexpr* is used to evaluate the most expensive statements. Always check if it actually improves performance for a specific problem. It can speed up the calculation for big arrays, but will most likely be slower for small arrays. It will use all available cores for these specific statements, which all contain *Gamma* in one way or another, which has dimensions (#frequencies, #offsets, #layers, #lambdas), therefore can grow pretty big. The module *numexpr* uses by default all available cores up to a maximum of 8. You can change this behaviour to your desired number of threads *nthreads* with *numexpr.set_num_threads(nthreads)*.
- If 'spline', the *lagged convolution* or *splined* variant of the FHT or the *splined* version of the QWE are used. Use with caution and check with the non-spline version for a specific problem. (Can be faster, slower, or plainly wrong, as it uses interpolation.) If spline is set it will make use of the parameter pts_per_dec that can be defined in htarg. If pts_per_dec is not set for FHT, then the *lagged* version is used, else the *splined*. This option has no effect on QUAD.

The option 'parallel' only affects speed and memory usage, whereas 'spline' also affects precision! Please read the note in the *README* documentation for more information.

loop : {None, 'freq', 'off'}, optional

Define if to calculate everything vectorized or if to loop over frequencies ('freq') or over offsets ('off'), default is None. It always loops over frequencies if ht = 'qwe' or if opt = 'spline'. Calculating everything vectorized is fast for few offsets OR for few frequencies. However, if you calculate many frequencies for many offsets, it might be faster to loop over frequencies. Only comparing the different versions will yield the answer for your specific problem at hand!

verb: {0, 1, 2, 3, 4}, optional

Level of verbosity, default is 2:

- 0: Print nothing.
- 1: Print warnings.
- 2: Print additional runtime and kernel calls
- 3: Print additional start/stop, condensed parameter information.
- 4: Print additional full parameter information

Returns EM: ndarray, (nfreq, nrec, nsrc)

Frequency- or time-domain EM field (depending on signal):

- If rec is electric, returns E [V/m].
- If rec is magnetic, returns B [T] (not H [A/m]!).

In the case of the impulse time-domain response, the unit is further divided by seconds [1/s].

However, source and receiver are normalised (unless strength != 0). So for instance in the electric case the source strength is 1 A and its length is 1 m. So the electric field could also be written as [V/(A.m2)].

In the magnetic case the source strength is given by $i\omega\mu_0AI^e$, where A is the loop area (m2), and I^e the electric source strength. For the normalized magnetic source $A=1m^2$ and $I^e=1Ampere$. A magnetic source is therefore frequency dependent.

The shape of EM is (nfreq, nrec, nsrc). However, single dimensions are removed.

See also:

fem Electromagnetic frequency-domain response.

tem Electromagnetic time-domain response.

Examples

```
>>> import numpy as np
>>> from empymod import bipole
>>> # x-directed bipole source: x0, x1, y0, y1, z0, z1
>>> src = [-50, 50, 0, 0, 100, 100]
>>> # x-directed dipole source-array: x, y, z, azimuth, dip
>>> rec = [np.arange(1, 11)*500, np.zeros(10), 200, 0, 0]
```

```
>>> # layer boundaries
>>> depth = [0, 300, 1000, 1050]
>>> # layer resistivities
>>> res = [1e20, .3, 1, 50, 1]
>>> # Frequency
>>> freq = 1
>>> # Calculate electric field due to an electric source at 1 Hz.
>>> # [msrc = mrec = True (default)]
>>> EMfield = bipole(src, rec, depth, res, freq, verb=4)
:: empymod START ::
  depth
           [m] : 0 300 1000 1050
          [Ohm.m] : 1E+20 0.3 1 50 1
  res
          [-]: 11111
  aniso
              [-]: 1 1 1 1 1
  epermH
  epermV
             [-]: 1 1 1 1 1
  mpermH
             [-]: 1 1 1 1 1
  mpermH
mpermV
             [-]: 1 1 1 1 1
  frequency [Hz]: 1
    ankel : Fast Hankel Transform > Filter : Key 201 (2009)
  Hankel
    > pts_per_dec : Defined by filter (lagged)
  Hankel Opt. : None
  Loop over
Source(s)
> intpts
                 : None (all vectorized)
                 : 1 bipole(s)
                 : 1 (as dipole)
    > length [m] : 100
    > x_c [m]: 0
> y_c [m]: 0
> z_c [m]: 100
    > azimuth [°] : 0
    > dip [°]: 0
  Receiver(s) : 10 dipole(s)
              [m] : 500 - 5000 : 10 [min-max; #]
                 : 500 1000 1500 2000 2500 3000 3500 4000 4500 5000
    > v
              [m] : 0 - 0 : 10 \quad [min-max; #]
                  : 0000000000
              [m] : 200
    > 7.
    > azimuth [°] :
                    0
    > dip [°]:
  Required ab's : 11
:: empymod END; runtime = 0:00:00.005536 :: 1 kernel call(s)
>>> print (EMfield)
[ 1.68809346e-10 -3.08303130e-10j -8.77189179e-12 -3.76920235e-11j
 -3.46654704e-12 -4.87133683e-12 -3.60159726e-13 -1.12434417e-12
  1.87807271e-13 -6.21669759e-13j 1.97200208e-13 -4.38210489e-13j
  1.44134842e-13 -3.17505260e-13i 9.92770406e-14 -2.33950871e-13i
   6.75287598e-14 -1.74922886e-13j 4.62724887e-14 -1.32266600e-13j]
```

 $\label{eq:continuous} \begin{array}{ll} \texttt{empymod.model.dipole} \ (src, rec, depth, res, freqtime, signal=None, ab=11, aniso=None, epermH=None, \\ epermV=None, \ mpermH=None, \ mpermV=None, \ xdirect=True, \ ht='fht', \\ htarg=None, ft='sin', ftarg=None, opt=None, loop=None, verb=2) \end{array}$

Return the electromagnetic field due to a dipole source.

Calculate the electromagnetic frequency- or time-domain field due to infinitesimal small electric or magnetic dipole source(s), measured by infinitesimal small electric or magnetic dipole receiver(s); sources and receivers

are directed along the principal directions x, y, or z, and all sources are at the same depth, as well as all receivers are at the same depth.

Use the functions bipole to calculate dipoles with arbitrary angles or bipoles of finite length and arbitrary angle.

The function *dipole* could be replaced by *bipole* (all there is to do is translate *ab* into *msrc*, *mrec*, *azimuth*'s and *dip*'s). However, *dipole* is kept separately to serve as an example of a simple modelling routine that can serve as a template.

Parameters src, rec: list of floats or arrays

Source and receiver coordinates (m): [x, y, z]. The x- and y-coordinates can be arrays, z is a single value. The x- and y-coordinates must have the same dimension.

Sources or receivers placed on a layer interface are considered in the upper layer.

depth: list

Absolute layer interfaces z(m); #depth = #res - 1 (excluding +/- infinity).

res: array_like

Horizontal resistivities rho_h (Ohm.m); #res = #depth + 1.

freqtime: array_like

Frequencies f (Hz) if signal == None, else times t (s); (f, t > 0).

signal: {None, 0, 1, -1}, optional

Source signal, default is None:

• None: Frequency-domain response

• -1 : Switch-off time-domain response

• 0 : Impulse time-domain response

• +1 : Switch-on time-domain response

ab: int, optional

Source-receiver configuration, defaults to 11.

		electric	electric source			magnetic source		
		X	y	Z	X	y	Z	
electric	X	11	12	13	14	15	16	
Ciccui ic	y	21	22	23	24	25	26	
receiver	Z	31	32	33	34	35	36	
magneti		41	42	43	44	45	46	
magnet	y	51	52	53	54	55	56	
receiver	Z	61	62	63	64	65	66	

aniso: array_like, optional

Anisotropies lambda = sqrt(rho_v/rho_h) (-); #aniso = #res. Defaults to ones.

epermH, epermV: array_like, optional

Relative horizontal/vertical electric permittivities epsilon_h/epsilon_v (-); #epermH = #epermV = #res. Default is ones.

mpermH, mpermV: array_like, optional

Relative horizontal/vertical magnetic permeabilities mu_h/mu_v (-); #mpermH = #mpermV = #res. Default is ones.

xdirect: bool, optional

If True and source and receiver are in the same layer, the direct field is calculated analytically in the frequency domain, if False it is calculated in the wavenumber domain. Defaults to True.

ht: {'fht', 'qwe', 'quad'}, optional

Flag to choose either the *Fast Hankel Transform* (FHT), the *Quadrature-With-Extrapolation* (QWE), or a simple *Quadrature* (QUAD) for the Hankel transform. Defaults to 'fht'.

htarg: dict or list, optional

Depends on the value for ht:

- If ht = 'fht': [filter, pts_per_dec]:
 - filter: string of filter name in empymod.filters or the method itself. (default: empymod.filters.key_201_2009())
 - pts_per_dec: points per decade (only relevant if spline=True)

If none, standard lagged convolution is used. (default: None)

• If ht = 'qwe': [rtol, atol, nquad, maxint, pts_per_dec,

diff_quad, a, b, limit]:

- rtol: relative tolerance (default: 1e-12)
- atol: absolute tolerance (default: 1e-30)
- nquad: order of Gaussian quadrature (default: 51)
- maxint: maximum number of partial integral intervals (default: 40)
- pts_per_dec: points per decade; only relevant if opt='spline' (default: 80)
- diff_quad: criteria when to swap to QUAD (only relevant if opt='spline') (default: 100)
- a: lower limit for QUAD (default: first interval from QWE)
- b: upper limit for QUAD (default: last interval from QWE)
- limit: limit for quad (default: maxint)
- If *ht* = 'quad': [atol, rtol, limit, lmin, lmax, pts_per_dec]:
 - rtol: relative tolerance (default: 1e-12)
 - atol: absolute tolerance (default: 1e-20)
 - limit: An upper bound on the number of subintervals used in the adaptive algorithm (default: 500)
 - lmin: Minimum wavenumber (default 1e-6)
 - lmax: Maximum wavenumber (default 0.1)
 - pts_per_dec: points per decade (default: 40)

The values can be provided as dict with the keywords, or as list. However, if provided as list, you have to follow the order given above. A few examples, assuming ht = qwe:

- Only changing rtol: {'rtol': 1e-4} or [1e-4] or 1e-4
- Changing rtol and nquad: {'rtol': 1e-4, 'nquad': 101} or [1e-4, '', 101]
- Only changing diff_quad: {'diffquad': 10} or [', ', ', ', ', ', 10]

```
ft: {'sin', 'cos', 'qwe', 'fftlog', 'fft'}, optional
```

Only used if *signal*!= None. Flag to choose either the Sine- or Cosine-Filter, the Quadrature-With-Extrapolation (QWE), the FFTLog, or the FFT for the Fourier transform. Defaults to 'sin'.

ftarg: dict or list, optional

Only used if *signal* !=None. Depends on the value for *ft*:

- If $ft = '\sin' \text{ or 'cos'}$: [filter, pts_per_dec]:
 - filter: string of filter name in empymod.filters or
 the filter method itself. (Default: empymod.filters.key_201_CosSin_2012())
 - pts_per_dec: points per decade. If none, standard lagged convolution is used. (Default: None)
- If ft = `qwe': [rtol, atol, nquad, maxint, pts_per_dec]:
 - rtol: relative tolerance (default: 1e-8)
 - atol: absolute tolerance (default: 1e-20)
 - nquad: order of Gaussian quadrature (default: 21)
 - maxint: maximum number of partial integral intervals (default: 200)
 - pts_per_dec: points per decade (default: 20)
 - diff_quad: criteria when to swap to QUAD (default: 100)
 - a: lower limit for QUAD (default: first interval from QWE)
 - b: upper limit for QUAD (default: last interval from QWE)
 - limit: limit for quad (default: maxint)
- If ft = 'fftlog': [pts per dec, add dec, q]:
 - pts_per_dec: sampels per decade (default: 10)
 - add_dec: additional decades [left, right] (default: [-2, 1])
 - q: exponent of power law bias (default: 0); $-1 \le q \le 1$
- If ft = 'fft': [dfreq, nfreq, ntot]:
 - dfreq: Linear step-size of frequencies (default: 0.002)
 - nfreq: Number of frequencies (default: 2048)
 - ntot: Total number for FFT; difference between nfreq and ntot is padded with zeroes. This number is ideally a power of 2, e.g. 2048 or 4096 (default: nfreq).

pts_per_dec : points per decade (default: None)

Padding can sometimes improve the result, not always. The default samples from 0.002 Hz - 4.096 Hz. If pts_per_dec is set to an integer, calculated frequencies are logarithmically spaced with the given number per decade, and then interpolated to yield the required frequencies for the FFT.

The values can be provided as dict with the keywords, or as list. However, if provided as list, you have to follow the order given above. See *htarg* for a few examples.

opt : {None, 'parallel', 'spline'}, optional

Optimization flag. Defaults to None:

- None: Normal case, no parallelization nor interpolation is used.
- If 'parallel', the package *numexpr* is used to evaluate the most expensive statements. Always check if it actually improves performance for a specific problem. It can speed up the calculation for big arrays, but will most likely be slower for small arrays. It will use all available cores for these specific statements, which all contain *Gamma* in one way or another, which has dimensions (#frequencies, #offsets, #layers, #lambdas), therefore can grow pretty big. The module *numexpr* uses by default all available cores up to a maximum of 8. You can change this behaviour to your desired number of threads *nthreads* with *numexpr.set_num_threads(nthreads)*.
- If 'spline', the *lagged convolution* or *splined* variant of the FHT or the *splined* version of the QWE are used. Use with caution and check with the non-spline version for a specific problem. (Can be faster, slower, or plainly wrong, as it uses interpolation.) If spline is set it will make use of the parameter pts_per_dec that can be defined in htarg. If pts_per_dec is not set for FHT, then the *lagged* version is used, else the *splined*. This option has no effect on QUAD.

The option 'parallel' only affects speed and memory usage, whereas 'spline' also affects precision! Please read the note in the *README* documentation for more information.

loop: {None, 'freq', 'off'}, optional

Define if to calculate everything vectorized or if to loop over frequencies ('freq') or over offsets ('off'), default is None. It always loops over frequencies if ht = 'qwe' or if opt = 'spline'. Calculating everything vectorized is fast for few offsets OR for few frequencies. However, if you calculate many frequencies for many offsets, it might be faster to loop over frequencies. Only comparing the different versions will yield the answer for your specific problem at hand!

verb: {0, 1, 2, 3, 4}, optional

Level of verbosity, default is 2:

- 0: Print nothing.
- 1: Print warnings.
- 2: Print additional runtime and kernel calls
- 3: Print additional start/stop, condensed parameter information.

• 4: Print additional full parameter information

Returns EM: ndarray, (nfreq, nrec, nsrc)

Frequency- or time-domain EM field (depending on signal):

- If rec is electric, returns E [V/m].
- If rec is magnetic, returns B [T] (not H [A/m]!).

In the case of the impulse time-domain response, the unit is further divided by seconds [1/s].

However, source and receiver are normalised. So for instance in the electric case the source strength is 1 A and its length is 1 m. So the electric field could also be written as [V/(A.m2)].

The shape of EM is (nfreq, nrec, nsrc). However, single dimensions are removed.

See also:

bipole Electromagnetic field due to an electromagnetic source.

fem Electromagnetic frequency-domain response.

tem Electromagnetic time-domain response.

Examples

```
>>> import numpy as np
>>> from empymod import dipole
>>> src = [0, 0, 100]
>>> rec = [np.arange(1, 11)*500, np.zeros(10), 200]
>>> depth = [0, 300, 1000, 1050]
>>> res = [1e20, .3, 1, 50, 1]
>>> EMfield = dipole(src, rec, depth, res, freqtime=1, verb=0)
>>> print(EMfield)
[ 1.68809346e-10 -3.08303130e-10j -8.77189179e-12 -3.76920235e-11j
-3.46654704e-12 -4.87133683e-12j -3.60159726e-13 -1.12434417e-12j
1.87807271e-13 -6.21669759e-13j 1.97200208e-13 -4.38210489e-13j
1.44134842e-13 -3.17505260e-13j 9.92770406e-14 -2.33950871e-13j
6.75287598e-14 -1.74922886e-13j 4.62724887e-14 -1.32266600e-13j]
```

Return the analytical full- or half-space solution.

Calculate the electromagnetic frequency- or time-domain field due to infinitesimal small electric or magnetic dipole source(s), measured by infinitesimal small electric or magnetic dipole receiver(s); sources and receivers are directed along the principal directions x, y, or z, and all sources are at the same depth, as well as all receivers are at the same depth.

In the case of a halfspace the air-interface is located at z = 0 m.

You can call the functions *fullspace* and *halfspace* in *kernel.py* directly. This interface is just to provide a consistent interface with the same input parameters as for instance for *dipole*.

This function yields the same result if *solution='fs'* as *dipole*, if the model is a fullspace.

Included are:

- Full fullspace solution (solution='fs') for ee-, me-, em-, mm-fields, [Hunziker_et_al_2015].
- Diffusive fullspace solution (*solution='dfs'*) for ee-fields, [Slob_et_al_2010].
- Diffusive halfspace solution (*solution='dhs'*) for ee-fields, [Slob_et_al_2010].

- Diffusive direct- and reflected field and airwave (solution='dsplit') for ee-fields, [Slob_et_al_2010].
- Diffusive direct- and reflected field and airwave (*solution='dtetm'*) for ee-fields, split into TE and TM mode [Slob et al 2010].

Parameters src, rec: list of floats or arrays

Source and receiver coordinates (m): [x, y, z]. The x- and y-coordinates can be arrays, z is a single value. The x- and y-coordinates must have the same dimension.

res: float

Horizontal resistivity rho_h (Ohm.m).

freqtime: array_like

Frequencies f (Hz) if signal == None, else times t (s); (f, t > 0).

solution: str, optional

Defines which solution is returned:

- 'fs': Full fullspace solution (ee-, me-, em-, mm-fields).
- 'dfs': Diffusive fullspace solution (ee-fields only).
- 'dhs': Diffusive halfspace solution (ee-fields only).
- 'dsplit' [Diffusive direct- and reflected field and airwave] (ee-fields only).
- 'dtetm' [as dsplit, but direct fielt TE, TM; reflected field TE, TM,] and airwave (ee-fields only).

signal: $\{None, 0, 1, -1\}$, optional

Source signal, default is None:

- None: Frequency-domain response
- -1 : Switch-off time-domain response
- 0 : Impulse time-domain response
- +1 : Switch-on time-domain response

ab: int, optional

Source-receiver configuration, defaults to 11.

		electric source			magnetic source		
x y z			X	y	Z		
electric	X	11	12	13	14	15	16
Ciccuic	y	21	22	23	24	25	26
receiver	Z	31	32	33	34	35	36
magneti		41	42	43	44	45	46
magnet	y	51	52	53	54	55	56
receiver	Z	61	62	63	64	65	66

aniso: float, optional

Anisotropy lambda = sqrt(rho_v/rho_h) (-); defaults to one.

epermH, epermV: float, optional

Relative horizontal/vertical electric permittivity epsilon_h/epsilon_v (-); default is one. Ignored for the diffusive solution.

mpermH, mpermV: float, optional

Relative horizontal/vertical magnetic permeability mu_h/mu_v (-); default is one. Ignored for the diffusive solution.

verb: {0, 1, 2, 3, 4}, optional

Level of verbosity, default is 2:

- 0: Print nothing.
- 1: Print warnings.
- 2: Print additional runtime
- 3: Print additional start/stop, condensed parameter information.
- 4: Print additional full parameter information

Returns EM: ndarray, (nfreq, nrec, nsrc)

Frequency- or time-domain EM field (depending on signal):

- If rec is electric, returns E [V/m].
- If rec is magnetic, returns B [T] (not H [A/m]!).

In the case of the impulse time-domain response, the unit is further divided by seconds [1/s].

However, source and receiver are normalised. So for instance in the electric case the source strength is 1 A and its length is 1 m. So the electric field could also be written as [V/(A.m2)].

The shape of EM is (nfreq, nrec, nsrc). However, single dimensions are removed.

If solution='dsplit', three ndarrays are returned: direct, reflect, air.

If *solution='dtetm'*, five ndarrays are returned: direct_TE, direct_TM, reflect_TE, reflect_TM, air.

Examples

```
>>> import numpy as np
>>> from empymod import analytical
>>> src = [0, 0, 0]
>>> rec = [np.arange(1, 11) *500, np.zeros(10), 200]
>>> res = 50
>>> EMfield = analytical(src, rec, res, freqtime=1, verb=0)
>>> print(EMfield)
[ 4.03091405e-08 -9.69163818e-10j 6.97630362e-09 -4.88342150e-10j
2.15205979e-09 -2.97489809e-10j 8.90394459e-10 -1.99313433e-10j
4.32915802e-10 -1.40741644e-10j 2.31674165e-10 -1.02579391e-10j
1.31469130e-10 -7.62770461e-11j 7.72342470e-11 -5.74534125e-11j
4.61480481e-11 -4.36275540e-11j 2.76174038e-11 -3.32860932e-11j]
```

Return the Ground-Penetrating Radar signal.

THIS FUNCTION IS EXPERIMENTAL, USE WITH CAUTION.

It is rather an example how you can calculate GPR responses; however, DO NOT RELY ON IT! It works only well with QUAD or QWE (*quad*, *qwe*) for the Hankel transform, and with FFT (*fft*) for the Fourier transform.

It calls internally *dipole* for the frequency-domain calculation. It subsequently convolves the response with a Ricker wavelet with central frequency *cf*. If signal!=None, it carries out the Fourier transform and applies a gain to the response.

For input parameters see the function *dipole*, except for:

Parameters cf: float

Centre frequency of GPR-signal, in Hz. Sensible values are between $10~\mathrm{MHz}$ and $3000~\mathrm{MHz}$.

gain: float

Power of gain function. If None, no gain is applied. Only used if signal!=None.

Returns EM: ndarray

GPR response

Return the electromagnetic wavenumber-domain field.

Calculate the electromagnetic wavenumber-domain field due to infinitesimal small electric or magnetic dipole source(s), measured by infinitesimal small electric or magnetic dipole receiver(s); sources and receivers are directed along the principal directions x, y, or z, and all sources are at the same depth, as well as all receivers are at the same depth.

Parameters src, rec: list of floats or arrays

Source and receiver coordinates (m): [x, y, z]. The x- and y-coordinates can be arrays, z is a single value. The x- and y-coordinates must have the same dimension. The x- and y-coordinates only matter for the angle-dependent factor.

Sources or receivers placed on a layer interface are considered in the upper layer.

depth: list

Absolute layer interfaces z(m); #depth = #res - 1 (excluding +/- infinity).

res: array_like

Horizontal resistivities rho_h (Ohm.m); #res = #depth + 1.

freq: array like

Frequencies f (Hz), used to calculate etaH/V and zetaH/V.

wavenumber : array

Wavenumbers lambda (1/m)

ab: int, optional

Source-receiver configuration, defaults to 11.

		electric	source		magnetic source		
	x y z			X	y	Z	
electric	X	11	12	13	14	15	16
	y	21	22	23	24	25	26
receiver	Z	31	32	33	34	35	36
magneti		41	42	43	44	45	46
magneti	y	51	52	53	54	55	56
receiver	Z	61	62	63	64	65	66

```
aniso: array_like, optional
```

Anisotropies lambda = sqrt(rho_v/rho_h) (-); #aniso = #res. Defaults to ones.

epermH, epermV: array_like, optional

Relative horizontal/vertical electric permittivities epsilon_h/epsilon_v (-); #epermH = #epermV = #res. Default is ones.

mpermH, mpermV: array_like, optional

Relative horizontal/vertical magnetic permeabilities mu_h/mu_v (-); #mpermH = #mpermV = #res. Default is ones.

verb: {0, 1, 2, 3, 4}, optional

Level of verbosity, default is 2:

- 0: Print nothing.
- 1: Print warnings.
- 2: Print additional runtime and kernel calls
- 3: Print additional start/stop, condensed parameter information.
- 4: Print additional full parameter information

Returns PJ0, PJ1: array

Wavenumber-domain EM responses:

- PJ0: Wavenumber-domain solution for the kernel with a Bessel function of the first kind of order zero.
- PJ1: Wavenumber-domain solution for the kernel with a Bessel function of the first kind of order one.

See also:

```
dipole Electromagnetic field due to an electromagnetic source (dipoles).

bipole Electromagnetic field due to an electromagnetic source (bipoles).

fem Electromagnetic frequency-domain response.

tem Electromagnetic time-domain response.
```

Examples

```
>>> import numpy as np
>>> from empymod.model import wavenumber
>>> src = [0, 0, 100]
>>> rec = [5000, 0, 200]
>>> depth = [0, 300, 1000, 1050]
>>> res = [1e20, .3, 1, 50, 1]
>>> freq = 1
>>> wavenrs = np.logspace(-3.7, -3.6, 10)
>>> PJ0, PJ1 = wavenumber(src, rec, depth, res, freq, wavenrs, verb=0)
>>> print (PJ0)
[ -1.02638329e-08 +4.91531529e-09j -1.05289724e-08 +5.04222413e-09j
 -1.08009148e-08 +5.17238608e-09j -1.10798310e-08 +5.30588284e-09j
 -1.13658957e-08 +5.44279805e-09j -1.16592877e-08 +5.58321732e-09j
 -1.19601897e-08 +5.72722830e-09j -1.22687889e-08 +5.87492067e-09j
 -1.25852765e-08 +6.02638626e-09j -1.29098481e-08 +6.18171904e-09j]
>>> print (PJ1)
[ 1.79483705e-10 -6.59235332e-10j 1.88672497e-10 -6.93749344e-10j
```

```
1.98325814e-10 -7.30068377e-10j 2.08466693e-10 -7.68286748e-10j 2.19119282e-10 -8.08503709e-10j 2.30308887e-10 -8.50823701e-10j 2.42062030e-10 -8.95356636e-10j 2.54406501e-10 -9.42218177e-10j 2.67371420e-10 -9.91530051e-10j 2.80987292e-10 -1.04342036e-09j]
```

empymod.model.fem(ab, off, angle, zsrc, zrec, lsrc, lrec, depth, freq, etaH, etaV, zetaH, zetaV, xdirect, isfullspace, ht, htarg, use_spline, use_ne_eval, msrc, mrec, loop_freq, loop_off, conv=True)

Return the electromagnetic frequency-domain response.

This function is called from one of the above modelling routines. No input-check is carried out here. See the main description of model for information regarding input and output parameters.

This function can be directly used if you are sure the provided input is in the correct format. This is useful for inversion routines and similar, as it can speed-up the calculation by omitting input-checks.

empymod.model.tem(fEM, off, freq, time, signal, ft, ftarg, conv=True)

Return the time-domain response of the frequency-domain response fEM.

This function is called from one of the above modelling routines. No input-check is carried out here. See the main description of model for information regarding input and output parameters.

This function can be directly used if you are sure the provided input is in the correct format. This is useful for inversion routines and similar, as it can speed-up the calculation by omitting input-checks.

kernel - Kernel calculation

Kernel of *empymod*, calculates the wavenumber-domain electromagnetic response. Plus analytical full- and half-space solutions.

The functions 'wavenumber', 'angle_factor', 'fullspace', 'greenfct', 'reflections', and 'fields' are based on source files (specified in each function) from the source code distributed with [Hunziker_et_al_2015], which can be found at software.seg.org/2015/0001. These functions are (c) 2015 by Hunziker et al. and the Society of Exploration Geophysicists, http://software.seg.org/disclaimer.txt. Please read the NOTICE-file in the root directory for more information regarding the involved licenses.

empymod.kernel.wavenumber (zsrc, zrec, lsrc, lrec, depth, etaH, etaV, zetaH, zetaV, lambd, ab, xdirect, msrc, mrec, use ne eval)

Calculate wavenumber domain solution.

Return the wavenumber domain solutions PJ0, PJ1, and PJ0b, which have to be transformed with a Hankel transform to the frequency domain. PJ0/PJ0b and PJ1 have to be transformed with Bessel functions of order 0 (J_0) and 1 (J_1) , respectively.

This function corresponds loosely to equations 105–107, 111–116, 119–121, and 123–128 in [Hunziker_et_al_2015], and equally loosely to the file *kxwmod.c.*

[Hunziker_et_al_2015] uses Bessel functions of orders 0, 1, and 2 (J_0, J_1, J_2) . The implementations of the *Fast Hankel Transform* and the *Quadrature-with-Extrapolation* in *transform* are set-up with Bessel functions of order 0 and 1 only. This is achieved by applying the recurrence formula

$$J_2(kr) = \frac{2}{kr}J_1(kr) - J_0(kr)$$
.

Note: *PJ0* and *PJ0b* could theoretically be added here into one, and then be transformed in one go. However, *PJ0b* has to be multiplied by *factAng* later. This has to be done after the Hankel transform for methods which make use of spline interpolation, in order to work for offsets that are not in line with each other.

This function is called from one of the Hankel functions in transform. Consult the modelling routines in model for a description of the input and output parameters.

If you are solely interested in the wavenumber-domain solution you can call this function directly. However, you have to make sure all input arguments are correct, as no checks are carried out here.

empymod.kernel.angle_factor(angle, ab, msrc, mrec)

Return the angle-dependent factor.

The whole calculation in the wavenumber domain is only a function of the distance between the source and the receiver, it is independent of the angel. The angle-dependency is this factor, which can be applied to the corresponding parts in the wavenumber or in the frequency domain.

The angle_factor corresponds to the sine and cosine-functions in Eqs 105-107, 111-116, 119-121, 123-128.

This function is called from one of the Hankel functions in transform. Consult the modelling routines in model for a description of the input and output parameters.

empymod.kernel.fullspace (off, angle, zsrc, zrec, etaH, etaV, zetaH, zetaV, ab, msrc, mrec)
Analytical full-space solutions in the frequency domain.

$$\hat{G}^{ee}_{\alpha\beta}, \hat{G}^{ee}_{3\alpha}, \hat{G}^{ee}_{33}, \hat{G}^{em}_{\alpha\beta}, \hat{G}^{em}_{\alpha3}$$

This function corresponds to equations 45–50 in [Hunziker_et_al_2015], and loosely to the corresponding files *Gin11.F90*, *Gin12.F90*, *Gin13.F90*, *Gin22.F90*, *Gin23.F90*, *Gin31.F90*, *Gin32.F90*, *Gin33.F90*, *Gin41.F90*, *Gin42.F90*, *Gin43.F90*, *Gin51.F90*, *Gin52.F90*, *Gin51.F90*, *Gin61.F90*, and *Gin62.F90*.

This function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

empymod.kernel.greenfct(zsrc, zrec, lsrc, lrec, depth, etaH, etaV, zetaH, zetaV, lambd, ab, xdirect,

msrc, mrec, use_ne_eval)

Calculate Green's function for TM and TE.

$$\tilde{g}_{hh}^{tm}, \tilde{g}_{hz}^{tm}, \tilde{g}_{zh}^{tm}, \tilde{g}_{zz}^{tm}, \tilde{g}_{hh}^{te}, \tilde{g}_{zz}^{te}$$

This function corresponds to equations 108–110, 117/118, 122; 89–94, A18–A23, B13–B15; 97–102 A26–A31, and B16–B18 in [Hunziker_et_al_2015], and loosely to the corresponding files *Gamma.F90*, *Wprop.F90*, *Ptotalx.F90*, *Ptotalxm.F90*, *Ptotaly.F90*, *Ptotalz.F90*, and *Ptotalzm.F90*.

The Green's functions are multiplied according to Eqs 105-107, 111-116, 119-121, 123-128; with the factors inside the integrals.

This function is called from the function kernel.wavenumber.

$$R_n^{\pm}, \bar{R}_n^{\pm}$$

This function corresponds to equations 64/65 and A-11/A-12 in [Hunziker_et_al_2015], and loosely to the corresponding files *Rmin.F90* and *Rplus.F90*.

This function is called from the function kernel.greenfct.

empymod.kernel.fields (depth, Rp, Rm, Gam, lrec, lsrc, zsrc, ab, TM, use_ne_eval) Calculate Pu+, Pu-, Pd+, Pd-.

$$P_s^{u\pm}, P_s^{d\pm}, \bar{P}_s^{u\pm}, \bar{P}_s^{d\pm}; P_{s-1}^{u\pm}, P_n^{u\pm}, \bar{P}_{s-1}^{u\pm}, \bar{P}_n^{u\pm}; P_{s+1}^{d\pm}, P_n^{d\pm}, \bar{P}_{s+1}^{d\pm}, \bar{P}_n^{d\pm}$$

This function corresponds to equations 81/82, 95/96, 103/104, A-8/A-9, A-24/A-25, and A-32/A-33 in [Hunziker_et_al_2015], and loosely to the corresponding files *Pdownmin.F90*, *Pdownplus.F90*, *Pupmin.F90*, and *Pdownmin.F90*.

This function is called from the function kernel.greenfct.

empymod.kernel.halfspace (off, angle, zsrc, zrec, etaH, etaV, freqtime, ab, signal, solution='dhs')
Return frequency- or time-space domain VTI half-space solution.

Calculates the frequency- or time-space domain electromagnetic response for a half-space below air using the diffusive approximation, as given in [Slob_et_al_2010], where the electric source is located at [0, 0, zsrc], and the electric receiver at [xco, yco, zrec].

It can also be used to calculate the fullspace solution or the separate fields: direct field, reflected field, and airwave; always using the diffusive approximation. See *solution*-parameter.

This routine is not strictly part of *empymod* and not used by it. However, it can be useful to compare the code to this analytical solution.

This function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and solution parameters.

transform - Hankel and Fourier Transforms

Methods to carry out the required Hankel transform from wavenumber to frequency domain and Fourier transform from frequency to time domain.

The functions for the QWE and FHT Hankel and Fourier transforms are based on source files (specified in each function) from the source code distributed with [Key_2012], which can be found at software.seg.org/2012/0003. These functions are (c) 2012 by Kerry Key and the Society of Exploration Geophysicists, http://software.seg.org/disclaimer.txt. Please read the NOTICE-file in the root directory for more information regarding the involved licenses.

empymod.transform.**fht** (zsrc, zrec, lsrc, lrec, off, angle, depth, ab, etaH, etaV, zetaH, zetaV, xdirect, fhtarg, use_spline, use_ne_eval, msrc, mrec)

Hankel Transform using the Fast Hankel Transform.

The *Fast Hankel Transform* is a *Digital Filter Method*, introduced to geophysics by [Gosh_1971], and made popular and wide-spread by [Anderson_1975], [Anderson_1979], [Anderson_1982].

This implementation of the FHT follows [Key_2012], equation 6. Without going into the mathematical details (which can be found in any of the above papers) and following [Key_2012], the FHT method rewrites the Hankel transform of the form

$$F(r) = \int_{0}^{\infty} f(\lambda) J_{v}(\lambda r) d\lambda$$

as

$$F(r) = \sum_{i=1}^{n} f(b_i/r)h_i/r ,$$

where h is the digital filter. The Filter abscissae b is given by

$$b_i = \lambda_i r = e^{ai}, \qquad i = -l, -l+1, \cdots, l,$$

with l = (n-1)/2, and a is the spacing coefficient.

This function is loosely based on get_CSEM1D_FD_FHT.m from the source code distributed with [Key_2012].

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

Returns fEM: array

Returns frequency-domain EM response.

kcount: int

Kernel count. For FHT, this is 1.

conv: bool

Only relevant for QWE/QUAD.

empymod.transform.hqwe (zsrc, zrec, lsrc, lrec, off, angle, depth, ab, etaH, etaV, zetaH, zetaV, xdirect, qweargs, use spline, use ne eval, msrc, mrec)

Hankel Transform using Quadrature-With-Extrapolation.

Quadrature-With-Extrapolation was introduced to geophysics by [Key_2012]. It is one of many so-called *ISE* methods to solve Hankel Transforms, where *ISE* stands for Integration, Summation, and Extrapolation.

Following [Key_2012], but without going into the mathematical details here, the QWE method rewrites the Hankel transform of the form

$$F(r) = \int_0^\infty f(\lambda) J_v(\lambda r) d\lambda$$

as a quadrature sum which form is similar to the FHT (equation 15),

$$F_i \approx \sum_{j=1}^m f(x_j/r)w_j g(x_j) = \sum_{j=1}^m f(x_j/r)\hat{g}(x_j)$$
,

but with various bells and whistles applied (using the so-called Shanks transformation in the form of a routine called ϵ -algorithm ([Shanks_1955], [Wynn_1956]; implemented with algorithms from [Trefethen_2000] and [Weniger_1989]).

This function is based on *get_CSEM1D_FD_QWE.m*, *qwe.m*, and *getBesselWeights.m* from the source code distributed with [Key_2012].

In the spline-version, *hqwe* checks how steep the decay of the wavenumber-domain result is, and calls QUAD for the very steep interval, for which QWE is not suited.

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

Returns fEM: array

Returns frequency-domain EM response.

kcount: int

Kernel count.

conv: bool

If true, QWE/QUAD converged. If not, <htarg> might have to be adjusted.

empymod.transform.hquad(zsrc, zrec, lsrc, lrec, off, angle, depth, ab, etaH, etaV, zetaH, zetaV, xdirect, quadargs, use_spline, use_ne_eval, msrc, mrec)

Hankel Transform using the QUADPACK library.

This routine uses the *scipy.integrate.quad* module, which in turn makes use of the Fortran library *QUADPACK* (*qagse*).

It is massively (orders of magnitudes) slower than either *fht* or *hqwe*, and is mainly here for completeness and comparison purposes. It always uses interpolation in the wavenumber domain, hence it generally will not be as precise as the other methods. However, it might work in some areas where the others fail.

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

Returns fEM: array

Returns frequency-domain EM response.

kcount: int

Kernel count. For HQUAD, this is 1.

conv: bool

If true, QUAD converged. If not, <htarg> might have to be adjusted.

empymod.transform.ffht (fEM, time, freq, ftarg)

Fourier Transform using a Cosine- or a Sine-filter.

It follows the Filter methodology [Anderson_1975], see *fht* for more information.

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

This function is based on get_CSEM1D_TD_FHT.m from the source code distributed with [Key_2012].

Returns tEM: array

Returns time-domain EM response of fEM for given time.

conv: bool

Only relevant for QWE/QUAD.

empymod.transform.fqwe(fEM, time, freq, qweargs)

Fourier Transform using Quadrature-With-Extrapolation.

It follows the QWE methodology [Key_2012] for the Hankel transform, see *hqwe* for more information.

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

This function is based on get_CSEM1D_TD_QWE.m from the source code distributed with [Key_2012].

fqwe checks how steep the decay of the frequency-domain result is, and calls QUAD for the very steep interval, for which QWE is not suited.

Returns tEM: array

Returns time-domain EM response of fEM for given time.

conv: bool

If true, QWE/QUAD converged. If not, <ftarg> might have to be adjusted.

empymod.transform.fftlog(fEM, time, freq, ftarg)

Fourier Transform using FFTLog.

FFTLog is the logarithmic analogue to the Fast Fourier Transform FFT. FFTLog was presented in Appendix B of [Hamilton 2000] and published at http://casa.colorado.edu/~ajsh/FFTLog.

This function uses a simplified version of *pyfftlog*, which is a python-version of *FFTLog*. For more details regarding *pyfftlog* see https://github.com/prisae/pyfftlog>.

Not the full flexibility of *FFTLog* is available here: Only the logarithmic FFT (*fftl* in *FFTLog*), not the Hankel transform (*fht* in *FFTLog*). Furthermore, the following parameters are fixed:

 $\bullet kr = 1$ (initial value)

• kropt = 1 (silently adjusts kr)

•dir = 1 (forward)

Furthermore, q is restricted to $-1 \le q \le 1$.

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

Returns tEM: array

Returns time-domain EM response of fEM for given time.

conv: bool

Only relevant for QWE/QUAD.

empymod.transform.fft (fEM, time, freq, ftarg)

Fourier Transform using the Fast Fourier Transform.

The function is called from one of the modelling routines in model. Consult these modelling routines for a description of the input and output parameters.

Returns tEM: array

Returns time-domain EM response of fEM for given time.

conv: bool

Only relevant for OWE/QUAD.

empymod.transform.**qwe** (*rtol*, *atol*, *maxint*, *inp*, *intervals*, *lambd=None*, *off=None*, *factAng=None*) Quadrature-With-Extrapolation.

This is the kernel of the QWE method, used for the Hankel (hqwe) and the Fourier (fqwe) Transforms. See hqwe for an extensive description.

This function is based on *qwe.m* from the source code distributed with [Key_2012].

```
empymod.transform.get_spline_values (filt, inp, nr_per_dec=None)
Return required calculation points.
```

empymod.transform.**fhti** (*rmin*, *rmax*, *n*, *q*, *mu*)

Return parameters required for FFTLog.

filters - Digital Filters for FHT

Filters for the Fast Hankel Transform (FHT, [Anderson_1982]) and the Fourier Sine and Cosine Transforms [Anderson_1975].

To calculate the fhtfilter.factor I used

```
np.around(np.average(fhtfilter.base[1:]/fhtfilter.base[:-1]), 15)
```

The filters $kong_61_2007$ and $kong_241_2007$ from [Kong_2007], and key_101_2009 , key_201_2009 , key_401_2009 , $key_81_CosSin_2009$, $key_81_CosSin_2009$, and $key_601_CosSin_2009$ from [Key_2009] are taken from DIPOLE1D, [Key_2009], which can be downloaded at marineemlab.ucsd.edu/Projects/Occam/1DCSEM. DIPOLE1D is distributed under the license GNU GPL version 3 or later. Kerry Key gave his written permission to re-distribute the filters under the Apache License, Version 2.0 (email from Kerry Key to Dieter Werthmüller, 21 November 2016).

The filters *anderson_801_1982* from [Anderson_1982] and *key_51_2012*, *key_101_2012*, *key_201_2012*, *key_101_CosSin_2012*, and *key_201_CosSin_2012*, all from [Key_2012], are taken from the software distributed with [Key_2012] and available at software.seg.org/2012/0003. These filters are distributed under the SEG license.

Anderson 801 pt filter, as published in [Anderson_1982]; taken from file *wa801Hankel.txt* from [Key_2012], published by the Society of Exploration Geophysicists; software.seg.org/2012/0003. License: http://software.seg.org/disclaimer.txt.

```
empymod.filters.key_101_2009()
Key 101 2009: [Key_2009].
```

Key 101 pt filter, as published in [Key_2009]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.key_101_2012()
Key 101 2012: [Key_2012].
```

Key 101 pt filter, taken from file *kk101Hankel.txt* from [Key_2012], published by the Society of Exploration Geophysicists; software.seg.org/2012/0003. License: http://software.seg.org/disclaimer.txt.

```
empymod.filters.key_101_CosSin_2012()
Key 101 CosSin 2012: [Key_2012].
```

Key 101 pt filter, taken from file *kk101CosSin.txt* from [Key_2012], published by the Society of Exploration Geophysicists; software.seg.org/2012/0003. License: http://software.seg.org/disclaimer.txt.

```
empymod.filters.key_201_2009()
Key 201 2009: [Key_2009].
```

Key 201 pt filter, as published in [Key_2009]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.key_201_2012()
Key 201 2012: [Key 2012].
```

Key 201 pt filter, taken from file *kk201Hankel.txt* from [Key_2012], published by the Society of Exploration Geophysicists; software.seg.org/2012/0003. License: http://software.seg.org/disclaimer.txt.

```
empymod.filters.key_201_CosSin_2012()
Key 201 CosSin 2012: [Key_2012].
```

Key 201 pt filter, taken from file *kk201CosSin.txt* from [Key_2012], published by the Society of Exploration Geophysicists; software.seg.org/2012/0003. License: http://software.seg.org/disclaimer.txt.

```
empymod.filters.key_241_CosSin_2009()
Key 241 CosSin 2009: [Key_2009].
```

Key 241 pt filter, as published in [Key_2009]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.key_401_2009()
Key 401 2009: [Key_2009].
```

Key 401 pt filter, as published in [Key_2009]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.key_51_2012()
Key 51 2012: [Key_2012].
```

Key 51 pt filter, taken from file *kk51Hankel.txt* from [Key_2012], published by the Society of Exploration Geophysicists; software.seg.org/2012/0003. License: http://software.seg.org/disclaimer.txt.

```
empymod.filters.key_601_CosSin_2009()
Key 601 CosSin 2009: [Key_2009].
```

Key 601 pt filter, as published in [Key_2009]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.key_81_CosSin_2009()
Key 81 CosSin 2009: [Key_2009].
```

Key 81 pt filter, as published in [Key_2009]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.kong_241_2007()
Kong 241: [Kong_2007].
```

Kong 241 pt filter, as published in [Kong_2007]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

```
empymod.filters.kong_61_2007()
Kong 61: [Kong_2007].
```

Kong 61 pt filter, as published in [Kong_2007]; taken from file *FilterModules.f90* from [Key_2009], available on marineemlab.ucsd.edu/Projects/Occam/1DCSEM. License: Apache License, Version 2.0, http://www.apache.org/licenses/LICENSE-2.0.

utils - Utilites

Utilities for *model* such as checking input parameters.

This module consists of four groups of functions:

- 0. General settings
- 1. Class EMArray
- 2. Input parameter checks for modelling
- 3. Internal utilities

 ${f class}$ empymod.utils.EMArray

Subclassing an ndarray: add amplitude <amp> and phase <pha>.

Parameters realpart: array

- 1. Real part of input, if input is real or complex.
- 2. Imaginary part of input, if input is pure imaginary.
- 3. Complex input.

In cases 2 and 3, *imagpart* must be None.

imagpart: array, optional

Imaginary part of input. Defaults to None.

Examples

Attributes

amp	(ndarray) Amplitude of the input data.	
pha	(ndarray) Phase of the input data, in degrees, lag-defined (increasing with increasing offset.) To get	
	lead-defined phases, multiply <i>imagpart</i> by -1 before passing through this function.	

```
empymod.utils.check_time_only(time, signal, verb)
```

Check time and signal parameters.

This check-function is called from one of the modelling routines in model. Consult these modelling routines for a detailed description of the input parameters.

Parameters time: array_like

Times t (s).

signal : {None, 0, 1, -1}

Source signal:

- None: Frequency-domain response
- -1 : Switch-off time-domain response
- 0 : Impulse time-domain response
- +1 : Switch-on time-domain response

verb: {0, 1, 2, 3, 4}

Level of verbosity.

Returns time: float

Time, checked for size and assured min_time.

```
empymod.utils.check_time (time, signal, ft, ftarg, verb)
```

Check time domain specific input parameters.

This check-function is called from one of the modelling routines in model. Consult these modelling routines for a detailed description of the input parameters.

```
Parameters time: array_like
```

Times t (s).

signal: {None, 0, 1, -1}

Source signal:

- None: Frequency-domain response
- -1 : Switch-off time-domain response
- 0 : Impulse time-domain response
- +1 : Switch-on time-domain response

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```
ft: {'sin', 'cos', 'qwe', 'fftlog', 'fft'}
                        Flag for Fourier transform.
                  ftarg: str or filter from empymod.filters or array_like,
                        Only used if signal !=None. Depends on the value for ft:
                  verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
            Returns time: float
                        Time, checked for size and assured min_time.
                  freq: float
                        Frequencies required for given times and ft-settings.
                  ft, ftarg
                        Checked if valid and set to defaults if not provided, checked with signal.
empymod.utils.check model (depth, res, aniso, epermH, epermV, mpermH, mpermV, xdirect, verb)
      Check the model: depth and corresponding layer parameters.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters depth: list
                        Absolute layer interfaces z(m); #depth = #res - 1 (excluding +/- infinity).
                  res: array_like
                        Horizontal resistivities rho_h (Ohm.m); \#res = \#depth + 1.
                  aniso: array_like
                        Anisotropies lambda = sqrt(rho_v/rho_h) (-); #aniso = #res.
                  epermH, epermV : array_like
                        Relative horizontal/vertical electric permittivities epsilon_h/epsilon_v (-);
                        \#epermH = \#epermV = \#res.
                  mpermH, mpermV: array_like
                        Relative horizontal/vertical magnetic permeabilities mu_h/mu_v (-); #mpermH
                        = #mpermV = #res.
                  xdirect: bool, optional
                        If True and source and receiver are in the same layer, the direct field is calculated
                        analytically in the frequency domain, if False it is calculated in the wavenumber
                        domain.
                  verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
            Returns depth: array
                        Depths of layer interfaces, adds -infty at beginning if not present.
                  res: array
                        As input, checked for size.
                  aniso: array
```

```
epermH, epermV : array_like
                        As input, checked for size. If None, defaults to an array of ones.
                  mpermH, mpermV: array_like
                        As input, checked for size. If None, defaults to an array of ones.
                 isfullspace: bool
                        If True, the model is a fullspace (res, aniso, epermH, epermV, mpermM, and
                        mpermV are in all layers the same).
empymod.utils.check_frequency (freq, res, aniso, epermH, epermV, mpermH, mpermV, verb)
     Calculate frequency-dependent parameters.
     This check-function is called from one of the modelling routines in model. Consult these modelling routines
     for a detailed description of the input parameters.
           Parameters freq: array_like
                        Frequencies f (Hz).
                  res : array_like
                        Horizontal resistivities rho_h (Ohm.m); \#res = \#depth + 1.
                 aniso: array_like
                        Anisotropies lambda = sqrt(rho_v/rho_h) (-); #aniso = #res.
                  epermH, epermV: array_like
                        Relative horizontal/vertical electric permittivities epsilon_h/epsilon_v (-);
                        #epermH = #epermV = #res.
                 mpermH, mpermV: array_like
                        Relative horizontal/vertical magnetic permeabilities mu_h/mu_v (-); #mpermH
                        = #mpermV = #res.
                 verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
           Returns freq: float
                        Frequency, checked for size and assured min_freq.
                  etaH, etaV: array
                        Parameters etaH/etaV, same size as provided resistivity.
                  zetaH, zetaV : array
                        Parameters zetaH/zetaV, same size as provided resistivity.
empymod.utils.check_hankel(ht, htarg, verb)
     Check Hankel transform parameters.
     This check-function is called from one of the modelling routines in model. Consult these modelling routines
     for a detailed description of the input parameters.
            Parameters ht: {'fht', 'qwe', 'quad'}
                        Flag to choose the Hankel transform.
                 htarg: str or filter from empymod.filters or array like,
```

As input, checked for size. If None, defaults to an array of ones.

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Depends on the value for ht.

```
verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
            Returns ht, htarg
                        Checked if valid and set to defaults if not provided.
empymod.utils.check_opt(opt, loop, ht, htarg, verb)
      Check optimization parameters.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters opt: {None, 'parallel', 'spline'}
                        Optimization flag.
                  loop : {None, 'freq', 'off'}
                        Loop flag.
                  ht: str
                        Flag to choose the Hankel transform.
                  htarg: array_like,
                        Depends on the value for ht.
                  verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
            Returns use_spline: bool
                        Boolean if to use spline interpolation.
                  use_ne_eval: bool
                        Boolean if to use numexpr.
                  loop_freq : bool
                        Boolean if to loop over frequencies.
                  loop off: bool
                        Boolean if to loop over offsets.
empymod.utils.check_dipole(inp, name, verb)
      Check dipole parameters.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters inp: list of floats or arrays
                        Pole coordinates (m): [pole-x, pole-y, pole-z].
                  name : str, { 'src', 'rec' }
                        Pole-type.
                  verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
            Returns inp: list
                        List of pole coordinates [x, y, z].
```

```
ninp: int
                        Number of inp-elements
empymod.utils.check_bipole(inp, name)
      Check di-/bipole parameters.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters inp: list of floats or arrays
                        Coordinates of inp (m): [dipole-x, dipole-y, dipole-z, azimuth, dip] or. [bipole-
                        x0, bipole-x1, bipole-y0, bipole-y1, bipole-z0, bipole-z1].
                  name : str, { 'src', 'rec' }
                        Pole-type.
            Returns inp: list
                        As input, checked for type and length.
                  ninp: int
                        Number of inp.
                  ninpz: int
                        Number of inp depths (ninpz is either 1 or ninp).
                  isdipole: bool
                        True if inp is a dipole.
empymod.utils.check_ab(ab, verb)
      Check source-receiver configuration.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters ab: int
                        Source-receiver configuration.
                  verb: {0, 1, 2, 3, 4}
                        Level of verbosity.
            Returns ab calc: int
                        Adjusted source-receiver configuration using reciprocity.
                  msrc, mrec: bool
                        If True, src/rec is magnetic; if False, src/rec is electric.
empymod.utils.check_solution(solution, signal, ab, msrc, mrec)
      Check required solution with parameters.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters solution: str
                        String to define analytical solution.
                  signal: {None, 0, 1, -1}
                        Source signal:
                                • None: Frequency-domain response
```

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```
• -1 : Switch-off time-domain response
```

• 0 : Impulse time-domain response

• +1 : Switch-on time-domain response

msrc, mrec: bool

True if src/rec is magnetic, else False.

empymod.utils.get_abs (msrc, mrec, srcazm, srcdip, recazm, recdip, verb)

Get required ab's for given angles.

This check-function is called from one of the modelling routines in model. Consult these modelling routines for a detailed description of the input parameters.

Parameters msrc, mrec: bool

True if src/rec is magnetic, else False.

srcazm, recazm: float

Horizontal source/receiver angle (azimuth).

srcdip, recdip : float

Vertical source/receiver angle (dip).

verb: {0, 1, 2, 3, 4}

Level of verbosity.

Returns ab_calc: array of int

ab's to calculate for this bipole.

empymod.utils.get_geo_fact (ab, srcazm, srcdip, recazm, recdip, msrc, mrec)

Get required geometrical scaling factor for given angles.

This check-function is called from one of the modelling routines in model. Consult these modelling routines for a detailed description of the input parameters.

Parameters ab: int

Source-receiver configuration.

srcazm, recazm: float

Horizontal source/receiver angle.

srcdip, recdip: float

Vertical source/receiver angle.

Returns fact: float

Geometrical scaling factor.

empymod.utils.get_azm_dip(inp, iz, ninpz, intpts, isdipole, strength, name, verb)

Get angles, interpolation weights and normalization weights.

This check-function is called from one of the modelling routines in model. Consult these modelling routines for a detailed description of the input parameters.

Parameters inp: list of floats or arrays

Input coordinates (m):

- [x0, x1, y0, y1, z0, z1] (bipole of finite length)
- [x, y, z, azimuth, dip] (dipole, infinitesimal small)

iz: int

```
Index of current di-/bipole depth (-).
                  ninpz: int
                         Total number of di-/bipole depths (ninpz = 1 or npinz = nsrc) (-).
                  intpts: int
                         Number of integration points for bipole (-).
                  isdipole: bool
                         Boolean if inp is a dipole.
                   strength: float, optional
                         Source strength (A):
                                 • If 0, output is normalized to source and receiver of 1 m length, and
                                   source strength of 1 A.
                                 • If != 0, output is returned for given source and receiver length, and
                                   source strength.
                  name : str, { 'src', 'rec' }
                         Pole-type.
                   verb: {0, 1, 2, 3, 4}
                         Level of verbosity.
            Returns tout: list of floats or arrays
                         Dipole coordinates x, y, and z (m).
                   azm: float or array of floats
                         Horizontal angle (azimuth).
                   dip: float or array of floats
                         Vertical angle (dip).
                   g_w: float or array of floats
                         Factors from Gaussian interpolation.
                  intpts: int
                         As input, checked.
                  inp_w: float or array of floats
                         Factors from source/receiver length and source strength.
empymod.utils.get_off_ang(src, rec, nsrc, nrec, verb)
      Get depths, offsets, angles, hence spatial input parameters.
      This check-function is called from one of the modelling routines in model. Consult these modelling routines
      for a detailed description of the input parameters.
            Parameters src, rec: list of floats or arrays
                         Source/receiver dipole coordinates x, y, and z (m).
                   nsrc, nrec: int
                         Number of sources/receivers (-).
                   verb: {0, 1, 2, 3, 4}
```

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```
Level of verbosity. Returns off: array of floats
```

Offsets

angle: array of floats

Angles

empymod.utils.get_layer_nr(inp, depth)

Get number of layer in which inp resides.

Note: If zinp is on a layer interface, the layer above the interface is chosen.

This check-function is called from one of the modelling routines in model. Consult these modelling routines for a detailed description of the input parameters.

Parameters inp: list of floats or arrays

Dipole coordinates (m)

depth: array

Depths of layer interfaces.

Returns linp: int or array_like of int

Layer number(s) in which inp resides (plural only if bipole).

zinp: float or array

inp[2] (depths).

empymod.utils.printstartfinish(verb, inp=None, kcount=None)

Print start and finish with time measure and kernel count.

empymod.utils.conv_warning(conv, targ, name, verb)

Print error if QWE/QUAD did not converge at least once.

CHAPTER 6

Indices and tables

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